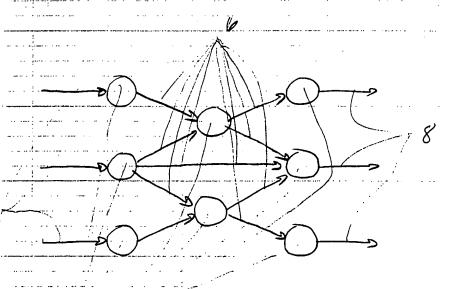
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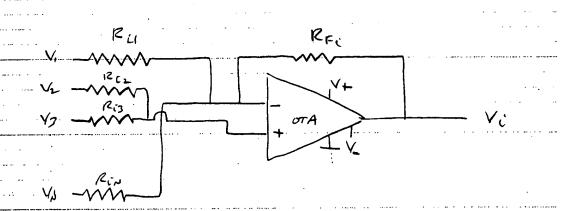
TI No /63/4 Sheet No 10f14

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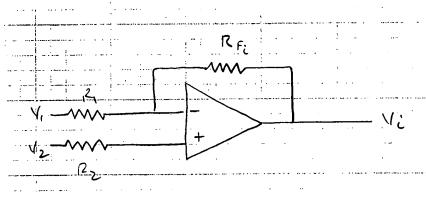
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FIGURE 8

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SUPPLY VOTABLES
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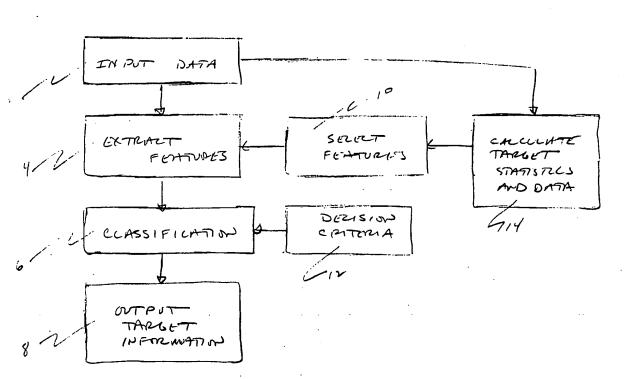
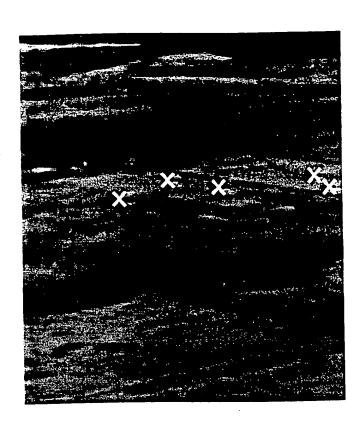


FIGURE 10

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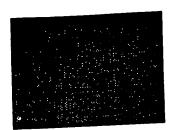


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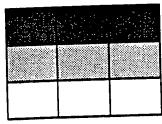
TI No ______ Of 14

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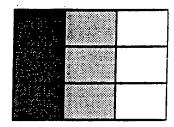
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Filter 1

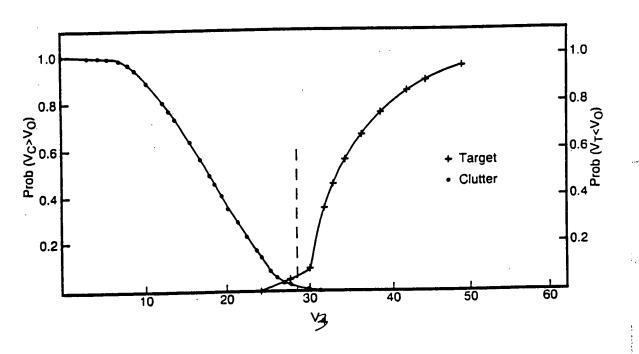


Filter 2



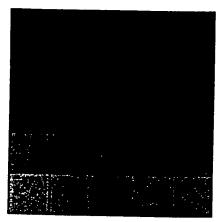
Filter 3

Fig 122



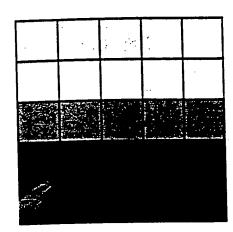
F10 26

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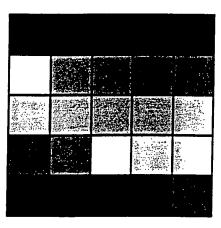
Filter 1 s/n = 1

FIG 13a



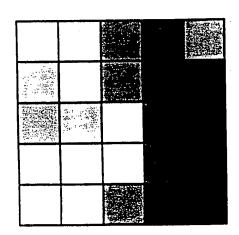
Filter 2 s/n = 7

Fig 3b



Filter 3 s/n = 7

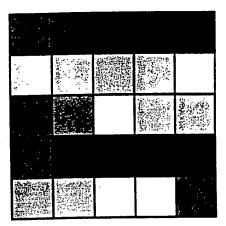
Fig. 13c



Filter 4 s/n = 5

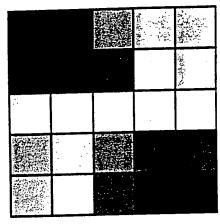
F12 10

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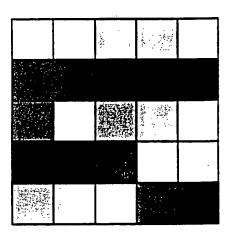
Filter 5 s/n = 23

FIG 13F



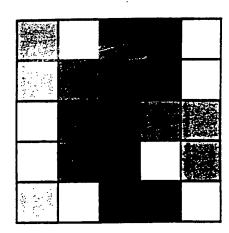
Filter 6 s/n = 8

FIG 13F



Filter 7 s/n = 13

Fig i, G



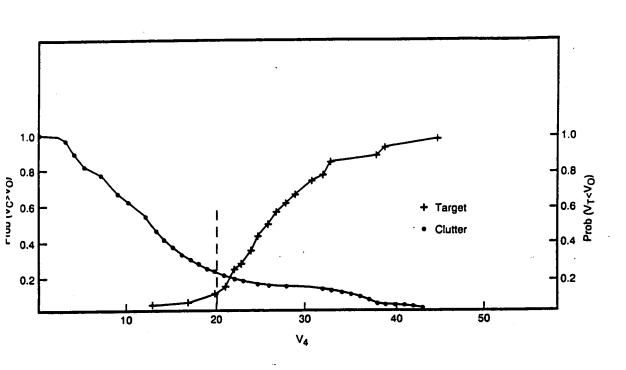
Filter $8 \, \text{s/n} = 9$

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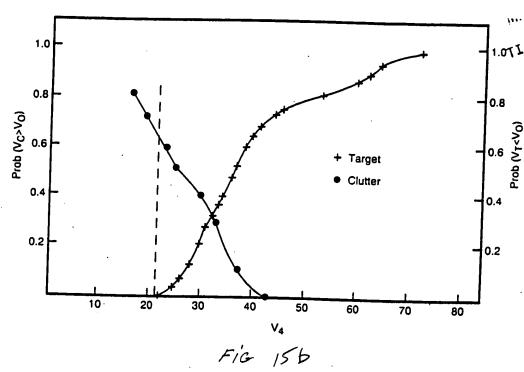


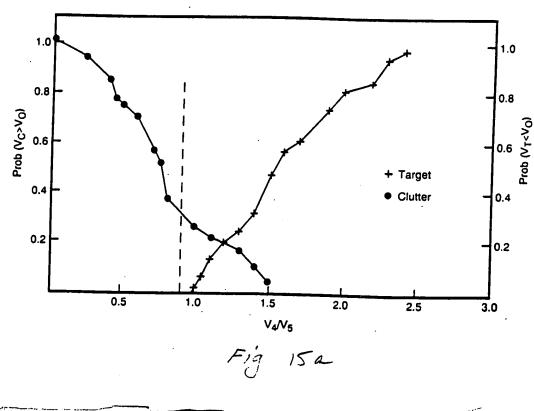
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PATENT SKETCH FORM

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```
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#define N 128
                    /* number of neurons in simulated network
#define C
           100
                    /* number of simulated time steps
#define POSITIVE_RAIL 15.0
                               /* Simulated power supply limits */
#define NEGATIVE_RAIL -15.0
#define Rf
                        0.001
                              /* Feedback resistance common to */
                               /* all neurons
main()
 double R[N][];
 double Vinitial(N);
 double Vnow[N];
 double sum;
 int c,i,j;
/* Get synapse list and copy initial neuron states into
   relaxation vector */
load_synapse matrix(R,N);
copy_first_vector into second(Vinitial, Vnow, N);
 for (c=0;c<C;c++)
                                   /* for C time steps
    for(i=0;i<N;i)
                                   /* for all neurons
      sum = 0.0;
      for(j=0;j<N;j++)
                                   /* get sum of products
       sum += (Rf/R[i][j])*Vnow[j];
      if (sum > POSITIVE RAIL)
                                   /* simulate ramp-threshold */
        Vnow[i] = POSITIVE RAIL;
      else
      if(sum < NEGATIVE_RAIL)</pre>
        Vnow[i] = NEGATIVE RAIL;
      else
        Vnow[i] = sum;
  }
print(Vnow);
                /* output final state of neurons */
} /* end of simulation program */
```

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Image Set	Number of Images	Location	Scene Description
1	4	G	а
2	2	G ·	l·· b
3	1	S	С
` 4	1	S	d
5	2	N	е

- a. Fields and Trees; Urban Clutter; Open and Partially Occluded Targets
- b. Fields; Urban Clutter; Targets in Openc. Fields; Urban Clutter; Targets in Open
- d. Heavy Forests; Partially Occluded Targets
- e. Fields and Heavy Forests; Partially Occluded Targets

Image Set	Number of Images	Location	Scene Description
1	21	S	Fields With Clusters of Trees; Urban Clutter; Open and Partially Occluded Targets.
2	3	N	Heavy Vegetation; Rural Clutter; Open targets.

Data Set II

TABLE II